



Motor drive MO710AZ(F)(N)ZNB Version 5V...

Drive unit for tubular motor with fail-safe function for fire screen.

Suitable for connection to a 230 V / 50 Hz tubular motor, permissible maximum power 1.8 kW (8A).



Wiring diagrams and instructions for use

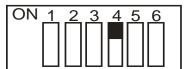
START by adjusting the correct type of limit switch

You can change the displaytext in Deutsch, Englisch, Nederlands and Polski Go to page 12 point 14 off this manual to see how you can do it.

Becker tubular motor type R60 has internally wired limit switches.

If the motor is fitted with **5 wire cores**, limit switches will not be connected to terminals 14, 16 and 18 (see diagram on page 2).

In this situation, the terminals are linked with bridging wires and **DIP switch 4** has to be in the **ON position**.

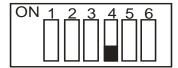


This drive is compliant with the following standards (among others):

Becker tubular motors R120 and R200 have externally wired limit switches.

The motor is fitted with 8 wire cores.

The external limit switches are connected to **terminals 14, 16 and 18** (see diagram on page 3), and **DIP switch 4** has to be in the **OFF position**.



EN 61000-6-1:2007-10	Electromagnetic Compatibility (EMC) - Part 6-1: Generic Standards- Immunity
	for Residential, Commercial and Light-industrial Environments
EN 61000-6-2:2006-3	Electromagnetic compatibility (EMC) Part 6-2: Generic standards - Immunity
	for industrial environments
EN 61000-6-3:2007-09	Electromagnetic compatibility (EMC) Part 6-3: Generic standards - Emission
	standard for residential, commercial and light-industrial environments
EN 61000-6-4:2007-09	Electromagnetic compatibility (EMC) Part 6-4: Generic standards - Emission
	standard for industrial environments
DIN EN 60335-1:2010-11	Household and similar electrical appliances - Safety - Part 1 General
	requirements
DIN EN 12445:2001-02	Industrial, commercial and garage doors and gates - Safety in use of power
	operated doors - Test methods
DIN EN 12453:2001-02	Industrial, commercial and garage doors and gates - Safety in use of power
	operated doors - Requirements (finalized version)
EN 12978:2003+A1:2009	Industrial, commercial and garage doors and gates. Safety devices for power
	operated doors and gates. Requirements and test methods
DIN EN ISO 13850:2008	Safety of machinery. Emergency stop. Principles for design

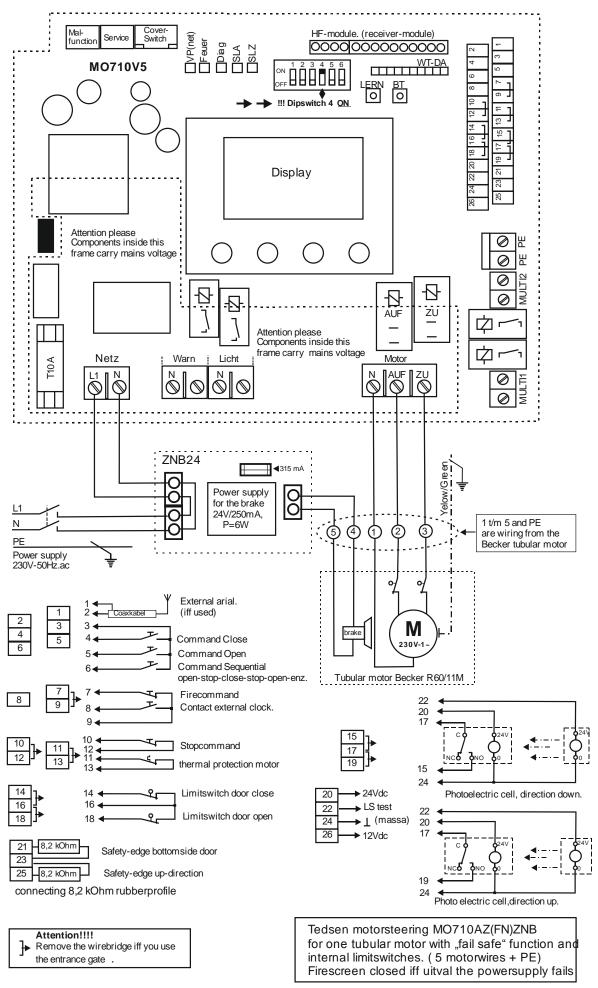
- Installation must be performed by an authorized installer.
- Before working on electrical installations, switch off the mains power supply.

The various connections and operating mechanisms are shown in the following diagrams.

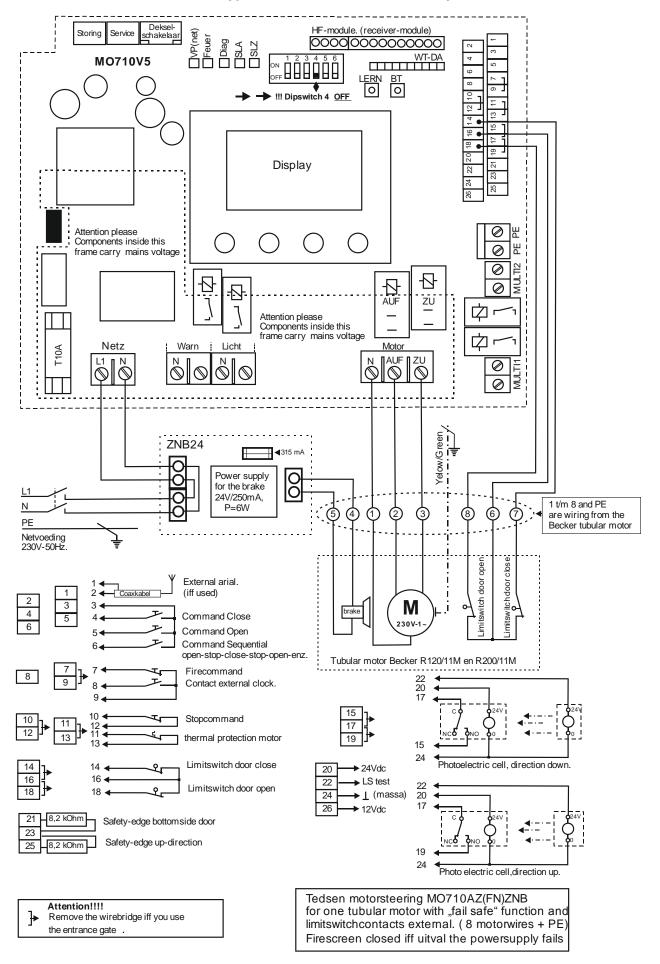
Tedsen drive MO710AZ(F)(N)ZNB

Description: Settings for each type of limit switch Standards and regulations with which the drive is compliant Contents Wiring diagram for motor with brake release, connected with 5 wire cores 1 3 Wiring diagram for motor with brake release, connected with 8 wire cores 2 4 Some wiring diagrams for connection from switches, fire-alarm and safety-edges. 3 5 Overview of the terminal blocks 4a 6 Description of connectors on the PCB Description of connectors on the PCB Description of additional connections Description of additional connections (optional) Add 6 DIP switch settings; modifying the drive to suit your requirements 5 6 and 7 Recommended work method 6 7 Method for connecting the motor Additional check of the DIP switch Adjusting the motor limit switches with a test cable and an MO drive 6.3 7 Making the final connections 7 8 Connecting the signal generators (operating switches, fire alarm(s), etc.) 7.2 8 Final checks 8 8 Checking the motor's direction of rotation 8.1 8 How to reverse the direction of rotation 8.1.1 8 How to reverse the direction of rotation 8.1.1 8 Setting up the complete drive 8.3 9 Connecting the signal generators Switching on the mains power supply 8.5 8 Checking the most important functions using the display 9 9 and 10 Learning the most important functions using the display 9 9 and 10 Learning the most important functions using the display 9 9 and 10 Learning the most important functions using the display 9 9 and 10 Learning the most important functions using the display 9 9 and 10 Learning the most important functions using the display 9 9 and 10 Learning the most important functions using the display 9 1 2 12 and 13 Software reset (this program should preferably not be used) 11 11 and 12 Learning radio codes (fhand-held) transmitters) 12 12 and 13 Software reset (this program should preferably not be used)	Contents:		
Settings for each type of limit switch Standards and regulations with which the drive is compliant Contents Wiring diagram for motor with brake release, connected with 5 wire cores 1 3 Wiring diagram for motor with brake release, connected with 5 wire cores 2 4 Some wiring diagrams for connection from switches, fire-alarm and safety-edges. 3 5 Coverview of the terminal blocks 4a 6 Description of connectors on the PCB 4b 6 Description of additional connections (optional) DIP switch settings; modifying the drive to suit your requirements 5 6 and 7 Recommended work method 6 7 Method for connecting the motor Additional check of the DIP switch Adjusting the motor limit switches with a test cable and an MO drive 6.3 7 Making the final connections 7 8 Connecting the signal generators (operating switches, fire alarm(s), etc.) 7 Setting the motor's direction of rotation 8.1 8 Checking the motor's direction of rotation 8.1.1 8 Setting up the complete drive 8.2 9 Setting up the complete drive 8.3 9 Connecting the signal generators Setting up the complete drive 8.3 9 Connecting the most important functions using the display 9 9 and 10 Learning the most important functions using the display 9 9 and 10 Learning the most important functions using the display 9 9 and 10 Learning the most important functions using the display 9 9 and 10 Learning the most important functions using the display 9 9 and 10 Learning the most important functions using the display 9 9 and 10 Learning the most important functions using the display 9 12 12 and 13 Software reset (this program should preferably not be used) 13 14 WatchTed® (security system with wireless sensors) 15 13 Mechanical and electrical specifications: 16		Section	Page
Standards and regulations with which the drive is compliant Contents 2 Wiring diagram for motor with brake release, connected with 5 wire cores 1 3 Wiring diagram for motor with brake release, connected with 8 wire cores 2 4 Some wiring diagrams for connection from switches, fire-alarm and safety-edges. 3 5 Overview of the terminal blocks 4a 6 Description of connectors on the PCB 4b 6 Description of the 230V connections 4c 6 Description of additional connections (optional) 4d 6 Diff switch settings; modifying the drive to suit your requirements 5 6 6 7 Method for connecting the motor 6 6 7 Additional check of the DIP switch 4 Adjusting the motor limit switches with a test cable and an MO drive 6 Adjusting the final connections 7 8 Connecting the signal generators (operating switches, fire alarm(s), etc.) 7 8 Connecting the motor's direction of rotation 8 1.1 8 Phow to reverse the direction of rotation 8 1.1 8 Setting up the complete drive 8 Setting up the complete drive 8 Switching on the mains power supply 8 Connecting the motor run-time (required operation) (Very important) 10 10 10 10 10 10 10 11 11 and 12 Learning the motor run-time (required operation) (Very important) 12 212 and 13 Software reset (this program should preferably not be used) 14 Metchanical and electrical specifications: 16 Mechanical and electrical specifications:			
Contents Wiring diagram for motor with brake release, connected with 5 wire cores 1 3 Wiring diagram for motor with brake release, connected with 8 wire cores 2 4 Some wiring diagrams for connection from switches, fire-alarm and safety-edges. 3 5 Overview of the terminal blocks 4a 6 Description of connectors on the PCB Description of the 230V connections Description of additional connections (optional) 4d 6 DIP switch settings; modifying the drive to suit your requirements 5 6 and 7 Recommended work method 6 7 Method for connecting the motor Additional check of the DIP switch 6.2 7 Additional check of the DIP switch 6.2 7 Addisting the motor limit switches with a test cable and an MO drive 6.3 7 Making the final connections 7 8 Connecting the signal generators (operating switches, fire alarm(s), etc.) 7 8 Checking the motor's direction of rotation 8.1 8 8 Checking the motor's direction of rotation 8.1.1 8 Setting up the complete drive 8.2 9 Switching on the mains power supply 8.5 8 Checking the most important functions using the display 9 9 and 10 10 10 10 10 10 10 10 10 11 11 and 12 Learning radio codes ((hand-held) transmitters) 12 12 and 13 Software reset (this program should preferably not be used) 15 13 Metchanical and electrical specifications: 16 14			1
Wiring diagram for motor with brake release, connected with 5 wire cores 1 3 Wiring diagram for motor with brake release, connected with 8 wire cores 2 4 Some wiring diagrams for connection from switches, fire-alarm and safety-edges. 3 5 Overview of the terminal blocks 4a 6 Description of connectors on the PCB 4b 6 Description of the 230V connections 4c 6 Description of diditional connections (optional) DIP switch settings; modifying the drive to suit your requirements 5 6 and 7 Recommended work method 6 7 Method for connecting the motor Additional check of the DIP switch Adjusting the motor limit switches with a test cable and an MO drive 6.3 7 Making the final connections Connecting the signal generators (operating switches, fire alarm(s), etc.) 7.2 8 Final checks 8 8 Checking the motor's direction of rotation 8.1 8 How to reverse the direction of rotation 8.1.1 8 Setting the limit switches Setting the limit switches Setting the signal generators Switching on the mains power supply Connecting the most important functions using the display Learning the motor run-time (required operation) (Very important) 10 Configuring (the operating settings) of the drive 11 and 12 Learning radio codes ((hand-held) transmitters) 12 and 13 Software reset (this program should preferably not be used) 15 Some optional settings Mechanical and electrical specifications: 16	Contents		2
Wiring diagram for motor with brake release, connected with 8 wire cores Some wiring diagrams for connection from switches, fire-alarm and safety-edges. Coverview of the terminal blocks Bescription of connectors on the PCB Description of connectors on the PCB Description of the 230V connections Description of additional connections (optional) DIP switch settings; modifying the drive to suit your requirements Some mended work method Recommended work method 6 7 Method for connecting the motor Additional check of the DIP switch Adjusting the motor limit switches with a test cable and an MO drive Adjusting the motor limit switches with a test cable and an MO drive Adjusting the signal generators (operating switches, fire alarm(s), etc.) Final checks Checking the motor's direction of rotation 8.1 8.1 8.1 8.2 9. Setting the limit switches 8.2 9. Setting the limit switches 8.2 9. Setting the most important functions using the display Connecting the most important functions using the display Checking the most important functions using the display Learning radio codes ((hand-held) transmitters) 10 Configuring (the operating settings) of the drive 11 11 and 12 Learning radio codes ((hand-held) transmitters) 12 13 and 14 WatchTed® (security system with wireless sensors) 14 13 Mechanical and electrical specifications:	Wiring diagram for motor with brake release, connected with 5 wire cores	1	
Some wiring diagrams for connection from switches, fire-alarm and safety-edges. Overview of the terminal blocks Description of connectors on the PCB Description of connectors on the PCB Description of the 230V connections Description of additional connections (optional) DIP switch settings; modifying the drive to suit your requirements 5 6 and 7 Recommended work method 6 7 Method for connecting the motor Additional check of the DIP switch Additional check of the DIP switch Sonnecting the signal generators (operating switches, fire alarm(s), etc.) To all the connections Checking the motor's direction of rotation How to reverse the direction of rotation Setting the limit switches Setting up the complete drive Connecting the signal generators Switching on the mains power supply Checking the most important functions using the display Personal the connections of the drive Configuring (the operating settings) of the drive Learning the most important settings) of the drive Configuring (the operating settings) of the drive Software reset (this program should preferably not be used) Methonical and electrical specifications: 16 14 Mechanical and electrical specifications:		2	4
Overview of the terminal blocks Description of connectors on the PCB Description of connectors on the PCB Description of the 230V connections Description of additional connections (optional) DIP switch settings; modifying the drive to suit your requirements 5 6 and 7 Recommended work method 6 7 Method for connecting the motor Additional check of the DIP switch Adjusting the motor limit switches with a test cable and an MO drive 6.3 7 Making the final connections 7 8 Connecting the signal generators (operating switches, fire alarm(s), etc.) 7.2 8 Final checks Checking the motor's direction of rotation 8.1 8 Checking the motor's direction of rotation 8.1.1 8 Setting the limit switches Setting up the complete drive 8.3 9 Connecting the signal generators Connecting the signal generators Switching on the mains power supply Checking the most important functions using the display Pochecking the most important functions using the display Dearning the most important functions		3	5
Description of the 230V connections Description of additional connections (optional) DIP switch settings; modifying the drive to suit your requirements Ecommended work method Recommended work method Method for connecting the motor Additional check of the DIP switch Additional check of the bip switch at test cable and an MO drive Adjusting the motor limit switches with a test cable and an MO drive Final connecting the signal generators (operating switches, fire alarm(s), etc.) Final checks Checking the motor's direction of rotation Ball Bal	Overview of the terminal blocks	4a	6
Description of additional connections (optional) DIP switch settings; modifying the drive to suit your requirements Example 1	Description of connectors on the PCB	4b	6
DIP switch settings; modifying the drive to suit your requirements 5 6 and 7 Recommended work method 6 7 Method for connecting the motor Additional check of the DIP switch 6.2 7 Adjusting the motor limit switches with a test cable and an MO drive 6.3 7 Making the final connections 7 8 Connecting the signal generators (operating switches, fire alarm(s), etc.) 7.2 8 Final checks Checking the motor's direction of rotation 8.1 8 How to reverse the direction of rotation 8.1.1 8 Setting the limit switches 8.2 9 Setting up the complete drive 8.3 9 Connecting the signal generators Switching on the mains power supply 8.5 8 Checking the most important functions using the display 9 9 and 10 Learning the motor run-time (required operation) (Very important) 10 10 Configuring (the operating settings) of the drive 11 11 and 12 Learning radio codes ((hand-held) transmitters) 20 Software reset (this program should preferably not be used) 13 14 WatchTed® (security system with wireless sensors) 14 13 Mechanical and electrical specifications: 16 14	Description of the 230V connections	4c	6
Recommended work method Method for connecting the motor Additional check of the DIP switch Adjusting the motor limit switches with a test cable and an MO drive Adjusting the final connections Tonacting the signal generators (operating switches, fire alarm(s), etc.) Connecting the signal generators (operating switches, fire alarm(s), etc.) The connecting the motor's direction of rotation Betting the motor's direction of rotation How to reverse the direction of rotation Setting the limit switches Setting up the complete drive Connecting the signal generators Setting up the motor runtien (required operation) Configuring the motor run-time (required operation) (Very important) Configuring (the operating settings) of the drive Learning radio codes ((hand-held) transmitters) Software reset (this program should preferably not be used) Method for connecting the signal generators 14 3 Mechanical and electrical specifications: 16 17 6.1 7 6.2 7 8.1 7 8.2 7 8.2 8 8 8 8 8 8 8 8 8 8 8 8 8	Description of additional connections (optional)	4d	6
Method for connecting the motor Additional check of the DIP switch Adjusting the motor limit switches with a test cable and an MO drive Adjusting the final connections Connecting the signal generators (operating switches, fire alarm(s), etc.) Final checks Checking the motor's direction of rotation How to reverse the direction of rotation Setting the limit switches Setting the signal generators Connecting the signal generators Setting up the complete drive Connecting the signal generators Switching on the mains power supply Checking the most important functions using the display Learning the motor run-time (required operation) (Very important) Configuring (the operating settings) of the drive Learning radio codes ((hand-held) transmitters) Software reset (this program should preferably not be used) WatchTed® (security system with wireless sensors) Mechanical and electrical specifications: 16 14	DIP switch settings; modifying the drive to suit your requirements	5	6 and 7
Additional check of the DIP switch Adjusting the motor limit switches with a test cable and an MO drive 6.3 7 Making the final connections 7 8 Connecting the signal generators (operating switches, fire alarm(s), etc.) 7.2 8 Final checks 8 Checking the motor's direction of rotation 8.1 8 How to reverse the direction of rotation 8.1.1 8 Setting the limit switches 8.2 9 Setting up the complete drive 8.3 Connecting the signal generators 8.4 9 Switching on the mains power supply 8.5 Checking the most important functions using the display 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	Recommended work method	6	7
Adjusting the motor limit switches with a test cable and an MO drive Making the final connections Connecting the signal generators (operating switches, fire alarm(s), etc.) Final checks Received the motor's direction of rotation How to reverse the direction of rotation Setting the limit switches Setting up the complete drive Connecting the signal generators Setting up the signal generators Switching on the mains power supply Checking the most important functions using the display Learning the motor run-time (required operation) (Very important) Configuring (the operating settings) of the drive Learning radio codes ((hand-held) transmitters) Software reset (this program should preferably not be used) WatchTed® (security system with wireless sensors) Mechanical and electrical specifications: 16 14	Method for connecting the motor	6.1	7
Making the final connections Connecting the signal generators (operating switches, fire alarm(s), etc.) Final checks Checking the motor's direction of rotation How to reverse the direction of rotation Setting the limit switches Setting up the complete drive Connecting the signal generators Switching on the mains power supply Checking the most important functions using the display Learning the motor run-time (required operation) (Very important) Configuring (the operating settings) of the drive Learning radio codes ((hand-held) transmitters) Software reset (this program should preferably not be used) WatchTed® (security system with wireless sensors) Mechanical and electrical specifications: 16 18 8 8 8 8 8 8 8 8 8 8 8 8	Additional check of the DIP switch	6.2	7
Making the final connections78Connecting the signal generators (operating switches, fire alarm(s), etc.)7.28Final checks88Checking the motor's direction of rotation8.18How to reverse the direction of rotation8.1.18Setting the limit switches8.29Setting up the complete drive8.39Connecting the signal generators8.49Switching on the mains power supply8.58Checking the most important functions using the display99 and 10Learning the motor run-time (required operation) (Very important)1010Configuring (the operating settings) of the drive1111 and 12Learning radio codes ((hand-held) transmitters)1212 and 13Software reset (this program should preferably not be used)1314WatchTed® (security system with wireless sensors)1413Some optional settings1513Mechanical and electrical specifications:1614	Adjusting the motor limit switches with a test cable and an MO drive	6.3	7
Final checks Checking the motor's direction of rotation How to reverse the direction of rotation Setting the limit switches Setting up the complete drive Setting up the signal generators Switching on the mains power supply Checking the most important functions using the display Searning the motor run-time (required operation) (Very important) Configuring (the operating settings) of the drive Learning radio codes ((hand-held) transmitters) Software reset (this program should preferably not be used) WatchTed® (security system with wireless sensors) Mechanical and electrical specifications: 8.1 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	Making the final connections	7	8
Checking the motor's direction of rotation8.18How to reverse the direction of rotation8.1.18Setting the limit switches8.29Setting up the complete drive8.39Connecting the signal generators8.49Switching on the mains power supply8.58Checking the most important functions using the display99 and 10Learning the motor run-time (required operation) (Very important)1010Configuring (the operating settings) of the drive1111 and 12Learning radio codes ((hand-held) transmitters)1212 and 13Software reset (this program should preferably not be used)1314WatchTed® (security system with wireless sensors)1413Some optional settings1513Mechanical and electrical specifications:1614	Connecting the signal generators (operating switches, fire alarm(s), etc.)	7.2	8
How to reverse the direction of rotation Setting the limit switches Setting up the complete drive Setting up the complete drive Connecting the signal generators Switching on the mains power supply Checking the most important functions using the display Learning the motor run-time (required operation) (Very important) Configuring (the operating settings) of the drive Learning radio codes ((hand-held) transmitters) Software reset (this program should preferably not be used) WatchTed® (security system with wireless sensors) Mechanical and electrical specifications: 18 8.1.1 8 8.2 9 9 9 11 10 10 10 10 11 11 1	Final checks	8	8
Setting the limit switches Setting up the complete drive Connecting the signal generators Switching on the mains power supply Checking the most important functions using the display Learning the motor run-time (required operation) (Very important) Configuring (the operating settings) of the drive Learning radio codes ((hand-held) transmitters) Software reset (this program should preferably not be used) WatchTed® (security system with wireless sensors) Some optional settings Mechanical and electrical specifications: 8.2 9 8.3 9 9 9 and 10 10 10 11 11 and 12 12 and 13 14 13 15 13	Checking the motor's direction of rotation	8.1	
Setting up the complete drive Connecting the signal generators Switching on the mains power supply Checking the most important functions using the display Learning the motor run-time (required operation) (Very important) Configuring (the operating settings) of the drive Learning radio codes ((hand-held) transmitters) Software reset (this program should preferably not be used) WatchTed® (security system with wireless sensors) Mechanical and electrical specifications: 8.4 9 8.4 9 9 and 10 10 10 11 11 and 12 12 and 13 14 13 14 13	How to reverse the direction of rotation	8.1.1	8
Connecting the signal generators Switching on the mains power supply Checking the most important functions using the display Learning the motor run-time (required operation) (Very important) Configuring (the operating settings) of the drive Learning radio codes ((hand-held) transmitters) Software reset (this program should preferably not be used) WatchTed® (security system with wireless sensors) Mechanical and electrical specifications: 8.4 9 8.5 8 10 11 11 11 11 11 11 11 11	Setting the limit switches	8.2	9
Switching on the mains power supply Checking the most important functions using the display 9 9 and 10 Learning the motor run-time (required operation) (Very important) 10 10 Configuring (the operating settings) of the drive 11 11 and 12 Learning radio codes ((hand-held) transmitters) 12 12 and 13 Software reset (this program should preferably not be used) 13 14 WatchTed® (security system with wireless sensors) 14 13 Some optional settings 15 13 Mechanical and electrical specifications: 16 14	Setting up the complete drive	8.3	9
Checking the most important functions using the display99 and 10Learning the motor run-time (required operation) (Very important)1010Configuring (the operating settings) of the drive1111 and 12Learning radio codes ((hand-held) transmitters)1212 and 13Software reset (this program should preferably not be used)1314WatchTed® (security system with wireless sensors)1413Some optional settings1513Mechanical and electrical specifications:1614	Connecting the signal generators	8.4	9
Learning the motor run-time (required operation) (Very important)1010Configuring (the operating settings) of the drive1111 and 12Learning radio codes ((hand-held) transmitters)1212 and 13Software reset (this program should preferably not be used)1314WatchTed® (security system with wireless sensors)1413Some optional settings1513Mechanical and electrical specifications:1614	Switching on the mains power supply	8.5	_
Configuring (the operating settings) of the drive1111 and 12Learning radio codes ((hand-held) transmitters)1212 and 13Software reset (this program should preferably not be used)1314WatchTed® (security system with wireless sensors)1413Some optional settings1513Mechanical and electrical specifications:1614	Checking the most important functions using the display	9	9 and 10
Learning radio codes ((hand-held) transmitters)1212 and 13Software reset (this program should preferably not be used)1314WatchTed® (security system with wireless sensors)1413Some optional settings1513Mechanical and electrical specifications:1614	Learning the motor run-time (required operation) (Very important)		10
Software reset (this program should preferably not be used) WatchTed® (security system with wireless sensors) Some optional settings Mechanical and electrical specifications: 13 14 13 15 13 14 15 16	Configuring (the operating settings) of the drive	11	11 and 12
WatchTed® (security system with wireless sensors)1413Some optional settings1513Mechanical and electrical specifications:1614	Learning radio codes ((hand-held) transmitters)	12	12 and 13
Some optional settings1513Mechanical and electrical specifications:1614	Software reset (this program should preferably not be used)	13	14
Some optional settings1513Mechanical and electrical specifications:1614	WatchTed® (security system with wireless sensors)	14	
	Some optional settings	15	13
Manufacturer's address details 14	Mechanical and electrical specifications:	16	14
	Manufacturer's address details		14

1. Connections for Becker motor type R60 with internally wired limit switches.

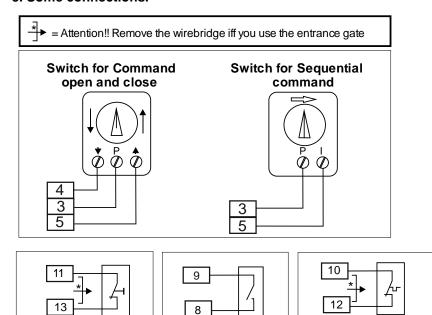


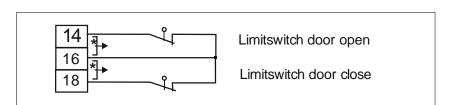
2. Connections for Becker motor types R120 and R200 with externally wired limit switches.



3. Some connections.

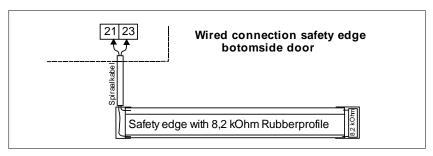
Stopcommand

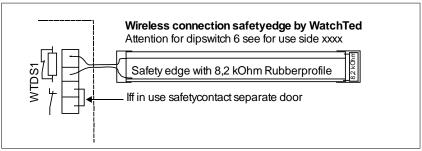


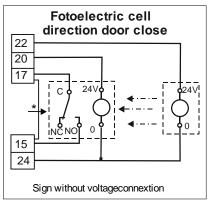


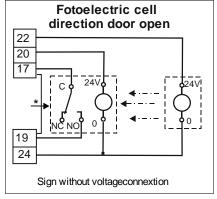
External Clock/Alarm

Command



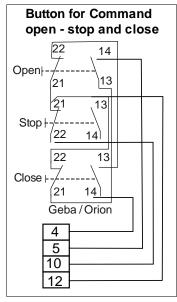


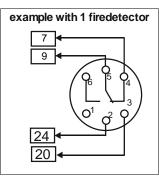


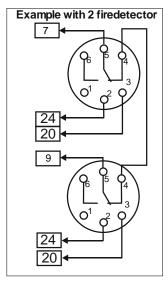


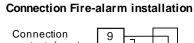
Contact for thermal

protection motor









contact close in safe situation (recommended)



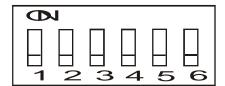
Mo710 control is the ex-factory prepared for a brandmeldcontact that is closed in safe condition.

The contact opens at a fire message. The controller recognizes the contact form in the program "learn motor maturity". Open or close on fire detection function can be selected in the configuration program with the ZS7.

4a. Overview of the terminal blocks

Inp		Input type	Function of the connection	Brief description	
Term	Terminals				
	1	Coaxial cable shielding (earth).		Is used for connecting an external	
2		Coaxial cable core antenna.			
	3	P contact for inputs 4,	5 and 6 (earthing contact).	Common	contact various inputs
4		'Close door' command		Pulse swit	ch (1 or 2 sided touch key)
	5	'Open door' command			ch (1 or 2 sided touch key)
6		Command sequence (oulse up-stop-down-stop-etc.)	Pulse swit	ch (1 sided touch key)
	7	Fire alarm contact (ma	ke or break contact)	Make/brea	ak contact. Fire alarm
8		SU input (door opens v			ole, contact alarm system.
	9		and 8 (earthing contact).	Common	for 'Feuer' (fire) and SU inputs
10		Stop command. (1st co		Breaks co	ntact between 10 and 12
	11		ontact thermal cut-out)	Breaks co	ntact between 11 and 13
12		Stop command (2nd co			ntact between 10 and 12
	13		ontact <i>thermal cut-out)</i>	Breaks co	ntact between 11 and 13
14			or closed (down direction)	Breaks co	ntact when end point is reached
	15	Breaks contact photoc	ell(s) door opening protection	Contact cl	osed in safety mode
16		P contact for both limit	switches (earthed)	Common	for inputs 14 and 18
	17	P contact for both phot	ocell inputs (earthed)	Common t	for inputs 15 and 19
18		External limit switch fo	r opening door (earthed)	Breaks co	ntact when end point is reached
	19	Breaks contact with ph	otocell(s) top entry protection		osed in safety mode
20		+ 24V/DC (power supp	ly for ext 24V/DC components)	Max. com	bined load 200mA 12 + 24V/DC
	21	Input for bottom edge	protection 8.2 kΩ and Fraba	Guards wi	th rubber profile
		lighting cove			
22		LS test 24V/DC for photocells with test function Common for SEA and		for SEA and SEZ	
	23	Earth connection for go	uards with rubber profile.		
24		Earth (-) connection for 12 and 24V/DC min. load 12 and 24V power		12 and 24V power	
	25			th rubber profile	
	cove				
26		+ 12V/DC (power supp	ly for ext 12V/DC components.	Max. com	bined load 200mA 12 + 24V/DC
<u> </u>					
		ion of connectors on			
HF Mo			Connector for receiver PCB EKXR710		
WTDA			onnector for WatchTed® module		loor protection unit)
3Kn-D			onnector for operating switch on		DOD 111 0 1
RELA	Y	Connector F	or connecting to an ARP24 PCB,	used auxili	iary PCB with a 3-phase motor
4c. De	escript	ion of the 230V conne	ctions:		
NETZ			ains power connections L1 and N	N .	
PE (2x)			Connection point for mains power earth		
WARN			or connection warning light	ourur	Red indicator light
		onnecting point for lamp (DIP5 O	F)(1-180 se		
			Multifunctional NO output contact.		Functions adjustable on display
MULTI 2			Multifunctional NO output contact.		Functions adjustable on display
.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	· <i>-</i>	1 romago noo IVI	aarioloriai ito oalput ooritatt.		1. dilottorio dajdotablo dil display
	4d. Description of additional connections:				
SERV			onnection for optional LED		Service indicator
STÖR	UNG		Connection for optional LED		Malfunction indicator
(malfu	ınction)				

5. Modifying the MO710 to suit your requirements and then using the unit.



With the 6-section DIP switch, various functions can be modified to suit your requirements.

The DIP switch is located on the PCB above the display.

(Text follow on next side)

DIP	Function	OFF position -	ON position
1	Drive operation for opening	Impulse (short press)	Dead man's operation
2	Drive operation for closing	Impulse (short press)	Dead man's operation
3	Automatic close	NO automatic close	Automatic close active
4	Limit switch type	See page 1 (settings for o	different types of limit switch)
5	Optional 'LIGHT' connection	Object illumination	Green indicator light when door is open
6	WatchTed protection	No function in case using a	a firescreen

! → ATTENTION: after changing a DIP switch position, the LERN (learn) key MUST be pressed and briefly held down to confirm the new function (TÜV requirement).

The 4 red LEDs (above the display) will briefly light up in sequence in confirmation.

If a DIP switch position is changed without giving confirmation by pressing the LERN key, the DIAG LED will continue to flash 2x on, 1x off, 2x on, etc. This will obviously only happen if the mains power is switched on.

6. Recommended work method

For your and other people's protection: WORK SAFELY!

Make sure that the door opening is and remains free of obstacles; mark off your work area.

6.1 Connections:

- With Becker motors with a 5-core connecting cable:
 - Connect motor wires 1, 2 and 3.
 - Connect the wires for the coupling (4 and 5) to the 24V power supply unit (small PCB).
- ➤ With Becker motors with a 8-core connecting cable:
 - Connect motor wires 1, 2 and 3.
 - Connect the brake wires 4 and 5 to the 24V power supply unit. (small PCB).
 - Connect the limit switch wires 6 (to terminal 16), 7 (to terminal 14) and 8 (to terminal 8).
- > **Do not** connect any photocells, the bottom edge and top entry protection or the control unit(s) for opening and closing the door yet.

6.2 Check DIP switch 4, ← ←! very important

- > <u>Indirect limit switches</u> (tubular motors with <u>5</u> connecting wires) are located together with their limit-switch wiring **inside** the motor housing.
 - ✓ Bridging wires have to be connected to terminals 16-14 and 16-18.
 - $\checkmark \rightarrow \rightarrow !$ DIP switch 4 must be ON.
- <u>Direct limit switches</u> (tubular motors with <u>8</u> connecting wires) have the limit-switch wires outside the motor housing and are connected to terminals 16-14 (door closed) and 16-18 (door open)
 - $\checkmark \rightarrow \Rightarrow$! DIP switch 4 must be OFF.

6.3 Adjust the motor limit switches correctly using a motor test cable.

- Connect motor wires 1 (zero), 2 and 3 (up and down) preferably with a motor test cable.
- Leave the brake wires 4 and 5 connected to the power supply PCB and make sure that the MO710 is also connected to the mains in order to power the 24V PCB.
- Set the up and down positions on the motor limit switches correctly.
- Additional help: with motors with an 8-core connecting cable, use the green LEDs, SEA (limit switch up) and SEZ (limit switch down) to assist you in making the settings.
 - To do this, the MO710 PCB must also be connected to mains.
- Setting the limit switches with a motor test cable is the easiest method.

> With the MO710AZ, if you do not have a motor test cable on hand:

- Create a provisionally operating system as follows: Connect a pulse switch for the up and down operations to 3 (P), 4 (down) and 5 (up)
- Or if there is an operating switch on the cover, connect it.
- Set DIP switches 1 and 2 to the ON position (dead man operating) press short the LERN key.
- √ Now set the motor limit-switches up and down correctly according the motor manual.

7. Making the final connections

- > 7.1 Connecting the motor (this only applies if the motor has not yet been connected)
 - Connect the motor following the instructions (see the respective wiring diagram on page 2 or 3, depending on the type of motor)
 - Use threaded bushes to prevent loose core wires from causing a short circuit.
 - Attention: the correct connections of the motor wires are: PE (earth) (green/yellow), up (open) (wire 2), down (closed) (wire 3) and zero (N) (wire 1).
 The up and down directions (wires 1 and 2) depend on the way in which the motor is installed and may have to be adjusted later on if the motor's direction of rotation is incorrect.

> 7.2 Connecting the signal generators

(See the appropriate wiring diagrams on pages 3, 4 and 5)

- Connect the required operating switches.
- Connect the contacts of stand-alone fire detectors or the fire alarm system (if used)
 when running the 'motor-run-time' learning program; the MO710 can detect the type of
 contact (NO or NC).

$|||| \rightarrow \rightarrow$ The fire alarm contact must be in 'condition safe' (no fire)

- Connect the mains power (if you have not already done so)
- The yellow LED above the display will go on; the display will light up and show initial
 information about possible malfunctions or connection errors.
 The 4 red LEDs above the display will quickly switch on and off in sequence (and should
 then remain off).
- Press short the LERN key (the left red key above the display).
 The 4 red LEDs will confirm that the LERN key has been pressed by switching on and off in sequence and then switching off.

Display

If the display does not show anything (blank screen) or does not respond, you can activate it by pressing any of the keys located under it.

Insert, if applicable, the receiver PCB for hand-held or other transmitters in the appropriate connector slot (connector 'HF Module'). Push the antenna onto its base. Insert, if applicable, the receiver PCB for the wireless transmission of commands to the bottom edge and top entry protection systems in the appropriate connector slot (connector 'WTDA').

8. Final checks

8.1 Checking the motor's direction of rotation

With the operating switch on the cover or with an operating switch connected to terminals 3-5 (up) and 3-4 (down), the motor's direction of rotation in **dead man's operation** can be checked.

Give an **up command**. (Keep the switch pressed down). The drive must raise the door **up**. Give a **down command**. (Keep the switch pressed). The drive must lower the door **down**.

TIP! If the motor only rotates in one direction when using the operating switch on the cover, the cable connecting the switch to the PCB may be twisted.

Rotate the plug attached to the flat connecting cable on the side of the cover 180°.

8.1.1 If the direction of rotation is incorrect, <u>switch off the mains power</u> and switch wires 2 and 3 attached to the motor's connections for up (open) and down (closed).

After doing this, reconnect the mains power and recheck the motor's direction of rotation by raising and lowering the door.

Make sure that the motor does not continue to run if the limit switches have not yet been set.

8.2 Setting the limit switches.

If the limit switches have already been set with, for example, a motor test cable, you can skip this point and continue under **7.3.**

If this is not the case, set the limit switches with a provisional operating system or with the operating switch on the cover (if present) connected to the MO710AZ.

ATTENTION! With motors that are connected with an 8-core cable, the 2 green LEDs on the PCB can assist you in setting the limit switches.

When the limit switch for open reaches the maximum **open** position, the green SE**A** LED will extinguish; when the limit switch for close reaches the maximum **closed** position, the green SE**Z** LED will extinguish.

If this is not the case, swap wires 7 and 8 attached to the SEA and SEZ terminals.

As an additional aid, you can set the limit switches on a motor with an 8-wire connecting cable by running the motor with the switches correctly wired up and down so that the green SEA LED extinguishes at the maximum open position and the green SEZ LED extinguishes at the maximum closed position.

If necessary, you can also set the limit switches with the MO710 drive.

In this case, you use the MO710 drive in the same way as a motor test cable. The difference is that the motor can be rotated in both directions in **dead man's operation** (DIP switches 1 and 2 in the ON position) with one up/down operating switch or with the switch on the cover.

! → We strongly advise against impulse operation (DIP 1 and 2 OFF) for safety reasons.

8.3 Setting up the complete drive

After disconnecting the mains power for safety reasons, we advise you to secure the fire screen in position to prevent it closing under its own weight when the brake system is not under current. If you want to connect peripheral equipment such as operating switches, etc. with the mains power switched on, be extra careful not to touch any parts of the PCB that are under current. (a market frame on the PCB)

8.4 Connecting the signal generators

Using the wiring diagrams on pages 1, 2 and 3, connect the required signal generators, such as operating switches, photocells, bottom edge and top entry protection, and, if necessary, the contacts for fire detectors or the fire alarm system. (**ATTENTION!** after connecting a fire detector or fire alarm system, run the 'motor run-times' learning program).

If necessary, read the instructions belonging to all peripheral equipment you wish to connect.

8.5 Check whether the mains power is switched on.

The 4 red LEDs above the display will go on one by one and then extinguish after switching on the mains power.

After the start-up sequence is complete, only the **yellow LED** will remain on to indicate that the unit is powered up.

After a few seconds, the display will show the function of the BA, BZ, BT and BS keys.

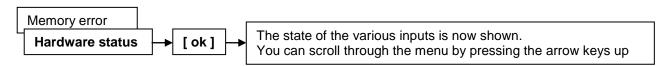
9. Checking the most important functions using the display

How to open the learning and configuration menu.

- a. Press the right black key [] (list symbol) on the display

 The initial PIN code 0 0 0 will be shown. (You can change the code later if you want it).
- b. Press the right arrow key $[\triangleright]$ briefly 4 times \rightarrow \rightarrow The menu will appear.

Use the <u>up and down arrow keys</u> $[\blacktriangle]$ [\blacktriangledown] to scroll through the menu; the following items will appear: (N.B. press the **home** key $[\frown]$ to return to the start screen)



The following circles have to be filled:

- o Fire alarm green, Contact fire alarm green.
- If the door is open: internal limit switch open green
- o If the door is closed: internal limit switch closed green
- Photocell mounted on door opening, photo cell for top entry protection, photocell for bottom edge protection,

12V power supply, 24V power supply, Radio - SLA0, SLZ1, TS0, TS1, **all green.** BATT0 and BATT1 are discussed below.

If necessary, various functions can now be checked, for example, interrupt the photocell beam in the door opening and the **green circle** after 'photocell door opening' should turn **red.**

10. Learning the motor run-time. $\rightarrow \rightarrow$! Running this program is <u>compulsory!</u>

$! \rightarrow \rightarrow$ Attention: the motor's limit switches <u>must</u> be set correctly.

While the 'motor run-time' program is in operation, the door opens and closes automatically. **Make sure the door opening is clear and free of obstacles.** The door will stop moving following a stop command or after pressing the button, for example, for the bottom edge protection or a photocell in the opening.

After a stop/emergency stop, the learning program has to be restarted.

It is advisable to put the drive in the down position (door closed).

This is not compulsory, but it does improve safety.

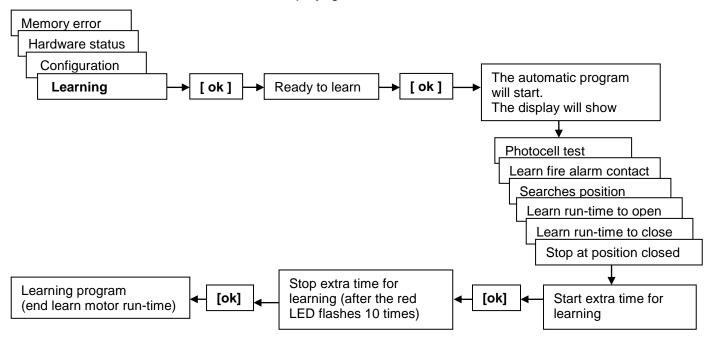
Bear in mind that the door will always try to shut first when learning the motor run-times. The drive will automatically detect whether the door is already closed.

Motor run-times learning program (largely a fully automatic program)

You can activate the display from sleep mode (dark screen) by pressing any of the 4 black keys.

If the start screen is shown on the display, start from here.

- a. Press the right black key [] (list symbol) on the display
 The initial PIN code 0 0 0 will be shown. (You can change the code later if you so choose).
- b Press the right arrow key [▶] briefly 4 times, → → The menu will appear.
 Use the up and down arrow keys [♠] [▼] to scroll through the menu; the following items will appear:
 - (N.B. By pressing the **home** key [\bigcirc] you can return to the start screen)
- \rightarrow If the **main menu** is shown on the display, go further below.



11. Configuring the controls

In the main menu, various control functions can be changed and modified.

A list of read-out and adjustment possibilities is given below.

Use the arrow keys to scroll through the menu.

When you reach a menu item you want to change, press [o.k.] and the respective submenu with the adjustment possibilities will be shown.

The displayed text indicates the possibilities that can be selected by pressing keys [▲] [▼].

You can activate the display from sleep mode (dark screen) by pressing any of the 4 black keys.

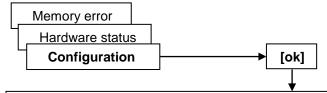
If the start screen is shown on the display, start from here.

- a. Press the right black key [] (list symbol) on the display

 The initial PIN code 0 0 0 will be shown. (You can change the code later).
- b. Press the right arrow key [▶] briefly 4 times, → → The menu will appear.
 Use the up and down arrow keys [▲] [▼] to scroll through the menu; the following items will appear:

(N.B. By press the **home** key [] you can go return to the start screen menu)

 \rightarrow If the **main menu** is shown on the display, you can continue below.



Use the arrow keys $[\blacktriangle]$ and $[\blacktriangledown]$ to scroll through the menu until you reach a function you want to edit. Select a function by pressing $[\omicronk]$, move to the next or previous function by pressing $[\blacktriangle]$ or $[\blacktriangledown]$, close

The display shows:	Possible action:	Option key	Information or action
Program version			Only information
Series number			Only information
Service counter	Shows the total number of movements		Only information
Operating hours counter	Shows total operating time		Only information
Maintenance counter	Maintenance interval reset	[▲] or [▼]	Delete yes/no
Maintenance interval	Maintenance interval setting	-1 or +1	Numerical adjustment
Keep open time 1	'Keep open time' setting (auto. close)	-1 or +1	0-300 sec.
Time to move out of the	Sets the amount of time to move out of	-1 or +1	0-300 sec.
way 1	the way (after passing through door		
	opening)		
Illumination time	Length of time lights are on (DIP 5 off)	-1 or +1	0-300 sec.
Repeat fire command	Closing after opening on receiving a fire	-1 or +1	0-300 sec.
	command		
User setting			
User setting save			
Load standard settings			
Indicator for opening	4 sec. warning before opening	[▲] or [▼]	Of or off → o.k.
Response to fire	Motor control after fire alarm has been	[▲] or [▼]	Open or close→
detection	given		
Closing after photocell	Activate quick close after passing	[▲] or [▼]	Switch on or switch off
beam interruption	through door opening		
Indicator for opening	Warning for opening	[▲] or [▼]	Flashing or continuous
Door in motion signal	Warning when door is in motion	[▲] or [▼]	Flashing or continuous
Signal to move out of the	Warning before the door closes	[▲] or [▼]	Flashing or continuous
way	-		_
Signal when door is	Warning that the door is closed	[▲] or [▼]	On or off
closed			
Signal that the door has	Warning that the door has stopped	[▲] or [▼]	On or off
stopped moving in mid	moving in mid cycle		
cycle			

Bottom edge protection	Response to activation of alarm on [▲] or [▼] Select function			Select function	
function		m edge rubber profile	[▲] or [▼]	0	
Photocell beam	Only	Only with barrier gate operation		On or off	
interruptions counter					
Lock over run-time	Monitors whether motor run-time is [▲] or [▼] On or off		On or off		
	exceeded				
	1	Service relay Contact closes after			
	2	Error message Contact closes after error message.			
	3		Multi 1 pulse	contact	
	4		Multi 1 on/of	f contact	
	5	Hand-held transmitter operation	Multi 2 pulse	contact	
	6		Multi 2 on/off contact		
	7		Make-and-break contact Multi1/2		
Multifunctional relay 1	8	For operating controller ASU1	Switches sim	nultaneously with	
and			controller AS		
Multifunctional relay 2	9	For operating controller ASU2	Switches sim	nultaneously with	
			controller AS		
	10		•		
	11	Message door open, voltage-free o	contact closes	when door is open.	
	12				
	13				
	14				
	' '	off)	9 5 5 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6		
	15	/			
	16	Error message relay. Contact p			
	17	Fire alarm N.O. contact for redirect			
	18	Slow speeds relays (Frequency co			
	19	Hydraulic retain valve			
Door closes after mains power failure		response to mains power failure	[▲] or [▼]	On or off	
WatchTed radio channel	Selects channel for the WatchTed -1 system		-1 or +1	Description on page 10	

12. Learning radio codes (transmitters, including hand-held)

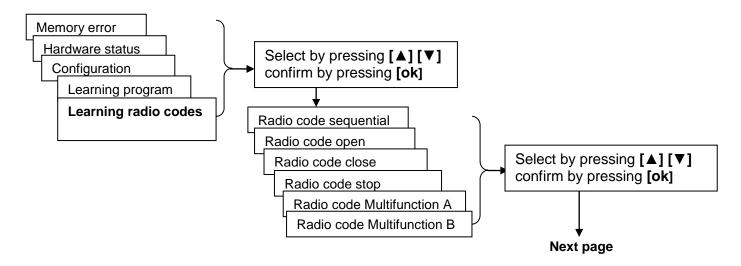
If the start screen is shown on the display, start from here.

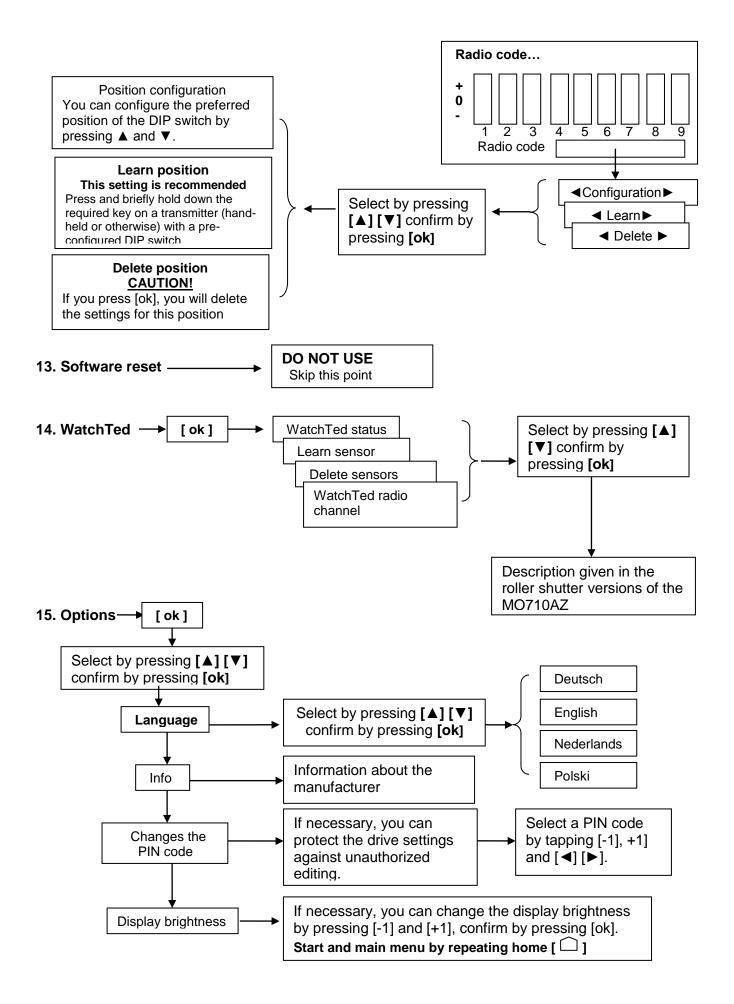
- a. Press the right black key [] (list symbol) on the display

 The initial PIN code 0 0 0 will be shown. (You can change the code later if you so choose).
- b. Press the right arrow key [▶] briefly 4 times → → The menu will appear.
 Use the up and down arrow keys [▲] [▼] to scroll through the menu; the following items will appear:

(N.B. press the **home** key [] to return to the start screen menu)

 \rightarrow If the **main menu** is shown on the display, continue below





16. Mechanical and electrical specifications.

Dimensions of the housing	L x B x H = 250 x 175 x 100 mm
Dimensions of the PCB	L X B = 144.5 x 133 mm
Power consumption in stand-by at	Approx. 1 Watt calculated with receiver and display ZS7, but without
230V/50Hz	any externally connected power consumers.
Mains power	230V/AC ± 10%, 50Hz.
Weight of PCB without housing	250 g.
Storage temperature	-20 °C to + 70 °C
Operating temperature	-10 °C to + 50 °C
Relative humidity	Max. 95% non-condensing
Connected load of motor	One 230V alternating current motor max. 10A, a 230V motor reverse
	relay for three-phase current motor or a relay box with 230V coils.
Protection class	With clamp fittings IP54, with PG sockets IP65.
Available power outlets for external	12Vdc - 100 mA and 24Vdc - 200 mA
equipment	
Measured motor output power	< 3 mA not detected, > 6mA detected.
	Max. permissible motor current 10A at 230V.
Noise level in free air	< 70dB(A)
Terminating resistance of guards	$8.2 \text{ k}\Omega \pm 5\%$ for guards with resistance measurement
Voltage measurement of the	5V ± 10%, 500Hz. to 2000Hz., 40% to 60% if no object is detected.
transmitter and receiver signals	
from a Fraba guard with slight	
transfer in the rubber profile.	



Adolf Tedsen GbmH & CO. KG Otto-Hahn- Strasse D – 22946 Trittau Tel: +49 (0)4154 – 3031 info@tdsen.com www.tedsen.com



Tedsen Teletaster Benelux B.V. Gebroeders Hermansstraat 2 NL – 6221 XM Maastricht Tel: +31 (0)43 3263684 info@tedsenbenelux.nl www.tedsen.com